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eralized Predictive Control (GPC) (Clarke et Al. 1987a, Clarke Et Al. 1987b). Although At Rst Sight The Ideas Underlying The DMC And GPC Are Simi-lar, DMC Was Conceived For

Multivariable Constrained Control, While GPC Is Primarily Suited For Single Variable, And Possibly Adaptive Control. The Conceptual Structure Of MPC Is Depicted In Fig. 1. 9th, 2024

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Control Policy Demonstrated. To This End, Robust Predictive Controllers Are Presented In Section 4.1 And The Predictive Controller Formulated To Satisfy The Switching Sequence Is Presented In Section 4.2. The Proposed Control Method Is Demonstrated Through Application To A Scheduled Chemical Process Example In Section 5. 2. PRELIMINARIES 16th, 2024

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