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2PM { 3:15PM, UH 4002 ffi Hours: Tuesdays

3:30PM{4:30PM (or By Appointment) Text: A Set Of  
Class Notes (evolved From Courses Taught By Several  
Faculty Members In The Department) Will Be Provided.  
These Notes Contain All De Nititions, Theorems, And  
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 Jiwen He Department Feb 10th, 2024  
 Some Linear Transformations On  $\mathbb{R}^2$  Math 130 Linear Algebra  
 That's An Expansion By A Factor Of 2. Note That Every Vector Is A 2-eigenvector. In Other Words, All Of  $\mathbb{R}^2$  Is The 2-eigenspace. Figure 6: Expansion Figure 7: Contraction Figure 8: Half Turn A Scalar Matrix Is A Multiple Of The Identity Matrix Like T May 10th, 2024  
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 18 (a) The System Has A Unique Solution; The Three Planes Have A Unique Point Of Intersection; (b) The System Has Infinitely Many Solutions; The Three Planes Intersect In A Line, Or The Three Planes Intersect In A Plane. ... -3x Apr 2th, 2024  
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 $A = Z \begin{pmatrix} 1 & Z+Y \\ 1 & Y+X \end{pmatrix} \begin{pmatrix} 1 & X \\ A=Z \end{pmatrix} \begin{pmatrix} 2 & Z+Y \\ 2 & Y+X \end{pmatrix} \begin{pmatrix} 2 & X \\ A=Z \end{pmatrix} \begin{pmatrix} 3 & Z+Y \\ 3 & Y+X \end{pmatrix} \begin{pmatrix} 3 & X \\ Z= \end{pmatrix} \begin{pmatrix} A & Y \\ 2 & X \end{pmatrix} \begin{pmatrix} 3 & A \\ 1 & Y \end{pmatrix} \begin{pmatrix} 3 & X \\ A & Y \end{pmatrix} \begin{pmatrix} 1 & X \\ 2 & Y \end{pmatrix}$   
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Number Of Nonzero Rows. The Number Of Nonzero Rows In  $R$  Is Called The Rank Of  $A$ , And Written  $\text{Rank}(A)$  (it Is Also The Rank Of  $R$ , Since  $R$  Is Already In REF). In The Rest Of These Notes Mar 5th, 2024.

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Projection Dimension Can Be Illustrated Using A "spike ... Be Rescaled To Have Unit Length By Dividing By Its Norm:  $\hat{v} = \frac{v}{\|v\|}$ . Geometrically, This Corresponds To Stacking The Vectors Head-to-foot.

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We want to extend the definition of Nullspace to general linear Transformations. Definition (NullSpace)

The nullspace of an  $m \times n$  Matrix  $A$  (denoted by  $\text{Null}(A)$ ) is the ... Feb 6th, 2024 Linear Algebra - Linear

Transformations Linear Transformations Kernel And Range Of A Linear Transformation • Theorem - Let  $L: V \rightarrow W$  Be A Linear Transformation A)  $\text{Ker } L$  Is A Subspace Of  $V$  B)  $L$  Is One To One If And Only If  $\text{Ker } L = \{0\}$  • Proof - A) Use The Theorem That Tests For Subspaces. Specifically, If  $U \subseteq V$  ... May 11th, 2024 Roberto's Notes On Linear Algebra Chapter 8: Linear ... Prove That A Linear Transformation From A Euclidean Space To Itself Is An Isomorphism If And Only If Its Kernel Is The Trivial Subspace. Templated Questions: 1. Construct A Linear Transformation And Then Identify Its Domain, Codomain, Range And Kernel. What Questions Do ... May 5th, 2024.

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